

# Image enhancement

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**Image enhancement** belongs to image pre-processing methods.

Objective of image enhancement – process the image (e.g. contrast improvement, image sharpening ,...) so that it is better suited for further processing or analysis

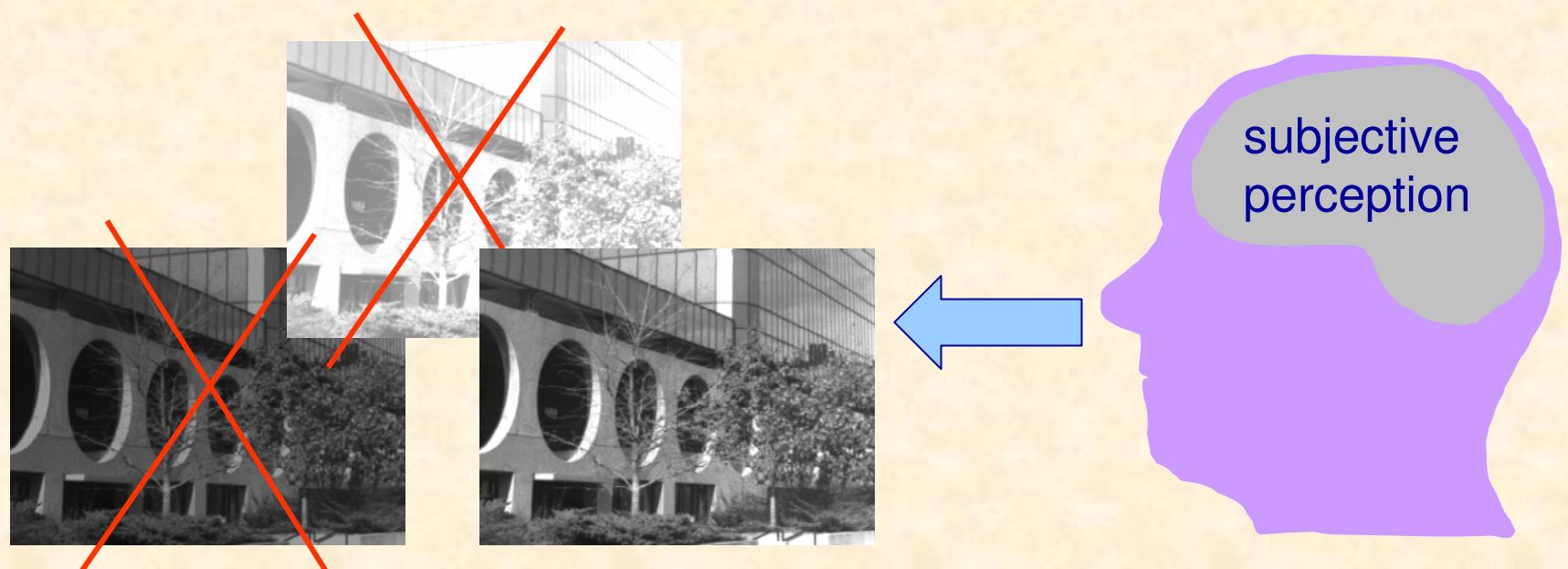


# Image enhancement

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Image enhancement methods are based on subjective image quality criteria.

No objective mathematical criteria are used for optimizing processing results.



# Image enhancement methods



## Point processing

Contrast enhancement

Histogram modelling

Image averaging



## Spatial filtering

Linear filters

Nonlinear filters

Edge detection

Zooming



## Image colouring

Pseudo colouring

False colouring

# Image enhancement

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Brightness

$$J = \frac{1}{MN} \sum_{i=1}^M \sum_{j=1}^N f(i, j)$$

Contrast

$$C = \sqrt{\frac{1}{MN} \sum_{i=1}^M \sum_{j=1}^N [f(i, j) - J]^2}$$

$M, N$  – image dimensions

$f(i, j)$  – gray level value at  $(i, j)$



## Image histogram

Image **brightness** and **contrast** influence image subjective quality perception



J=112, C=47



J=29, C=38

# Image histogram

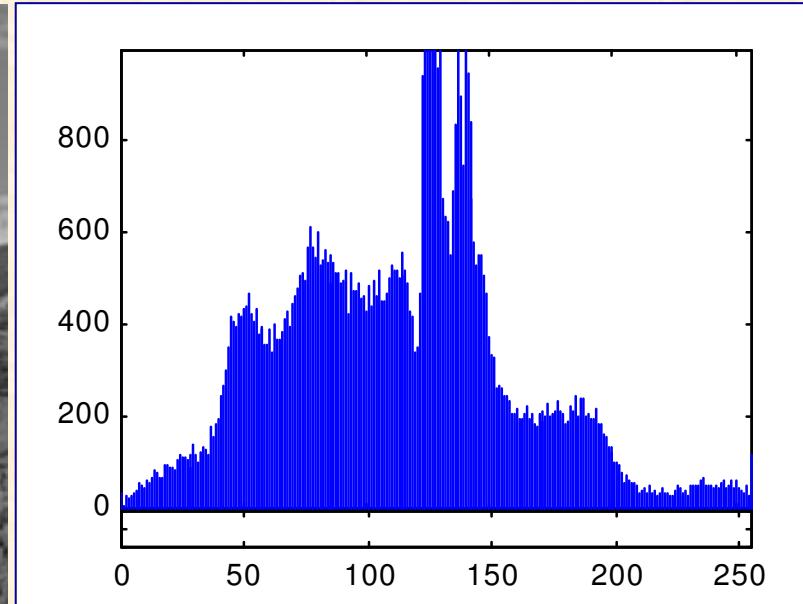


Image : array[1..M,1..N] of byte;

Hist : array[0..L-1] of longint;

...

Hist:=0;

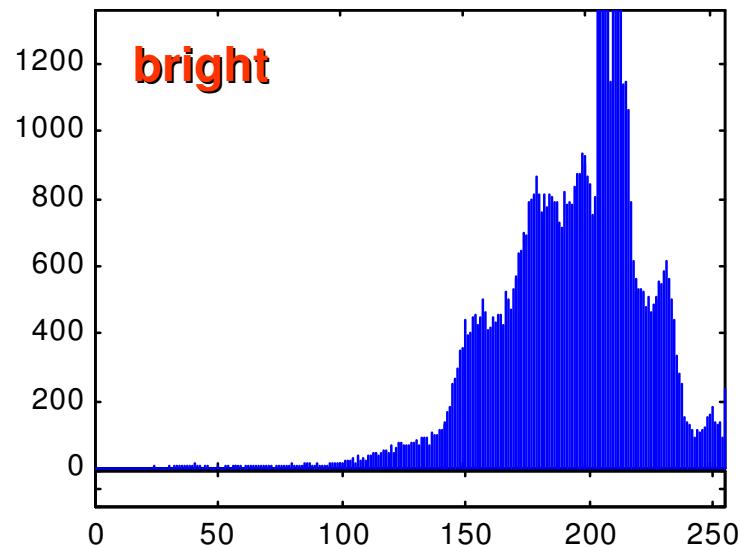
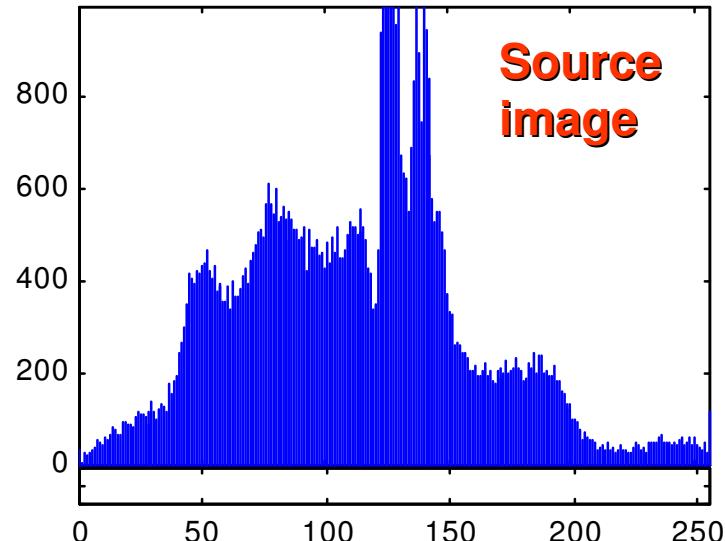
for i:=1 to M do for j:=1 to N do

    Inc( Hist[ Image[i, j] ] );

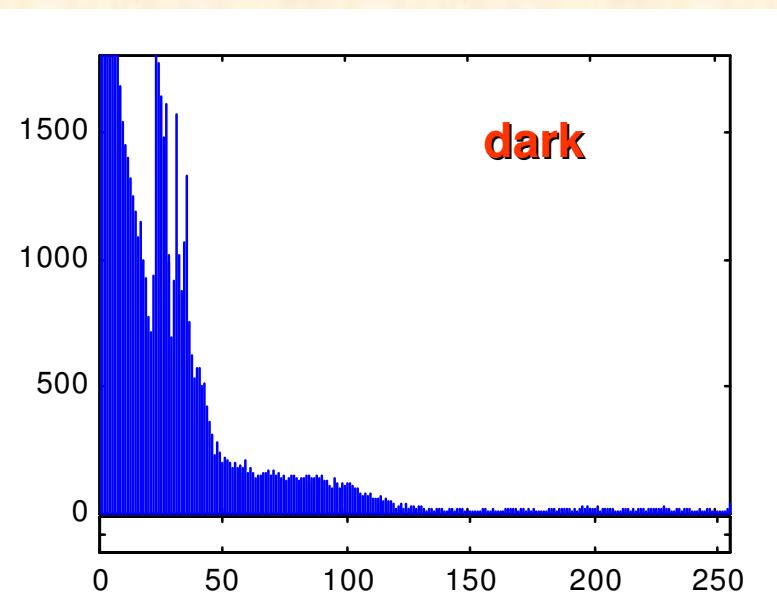
...

imhist(I)

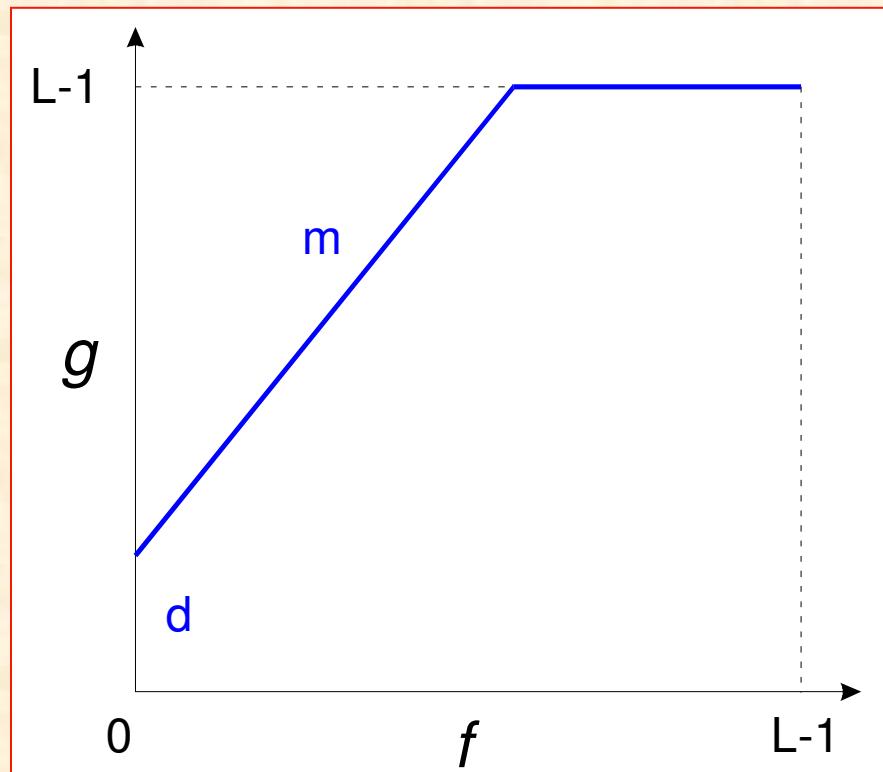
# Image histogram



**Image histogram**  
represents statistical  
distribution of image  
pixel brightnesses



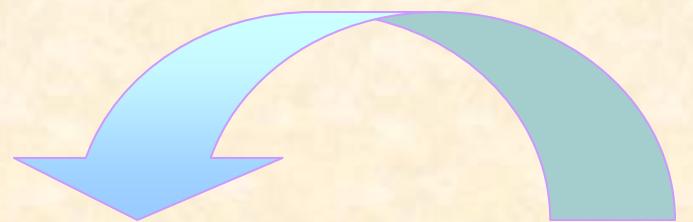
# Linear gray scale transformation



$m \sim$  contrast

$d \sim$  brightness

$$g(i,j) = m f(i,j) + d$$

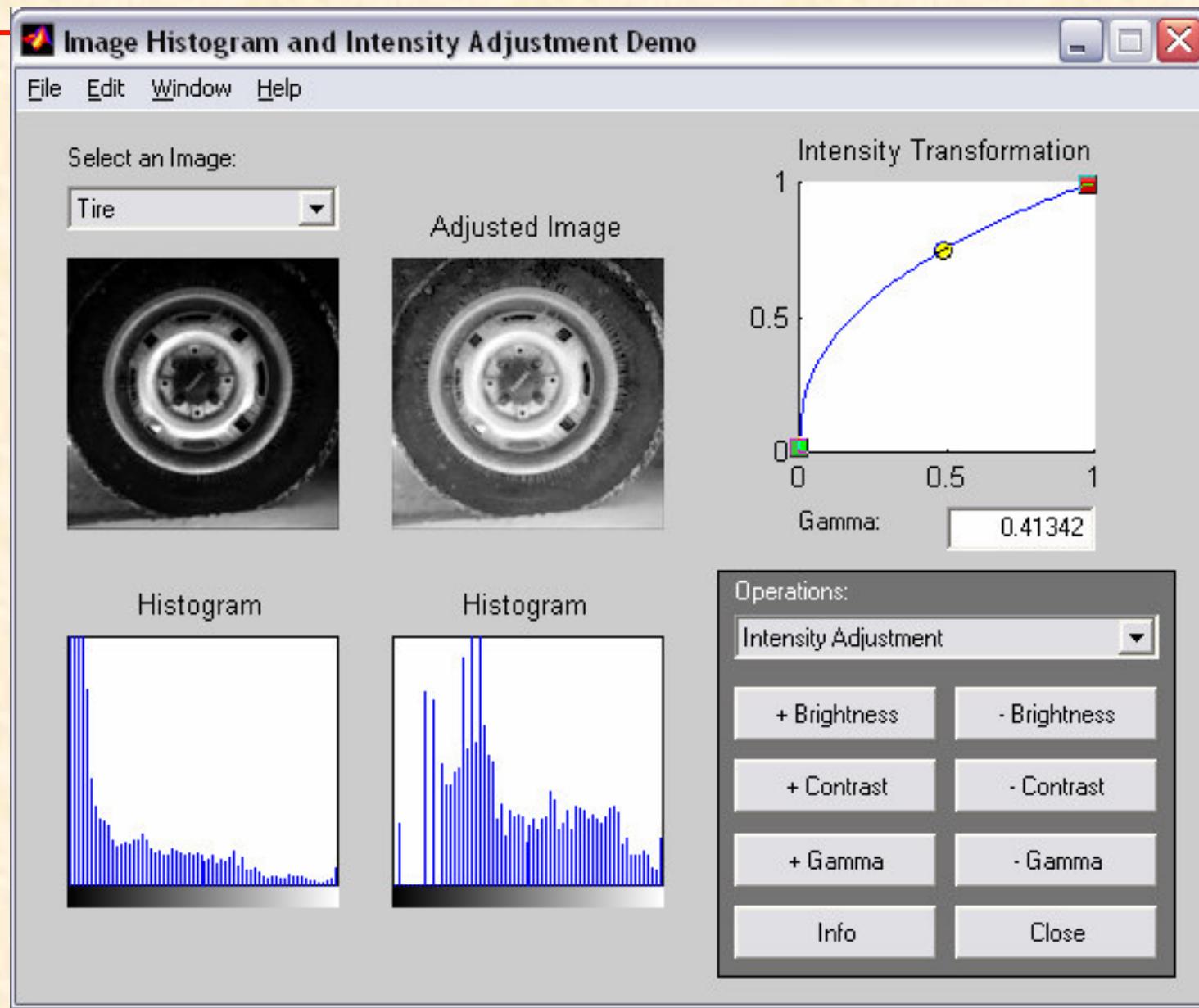


OUTPUT  
IMAGE

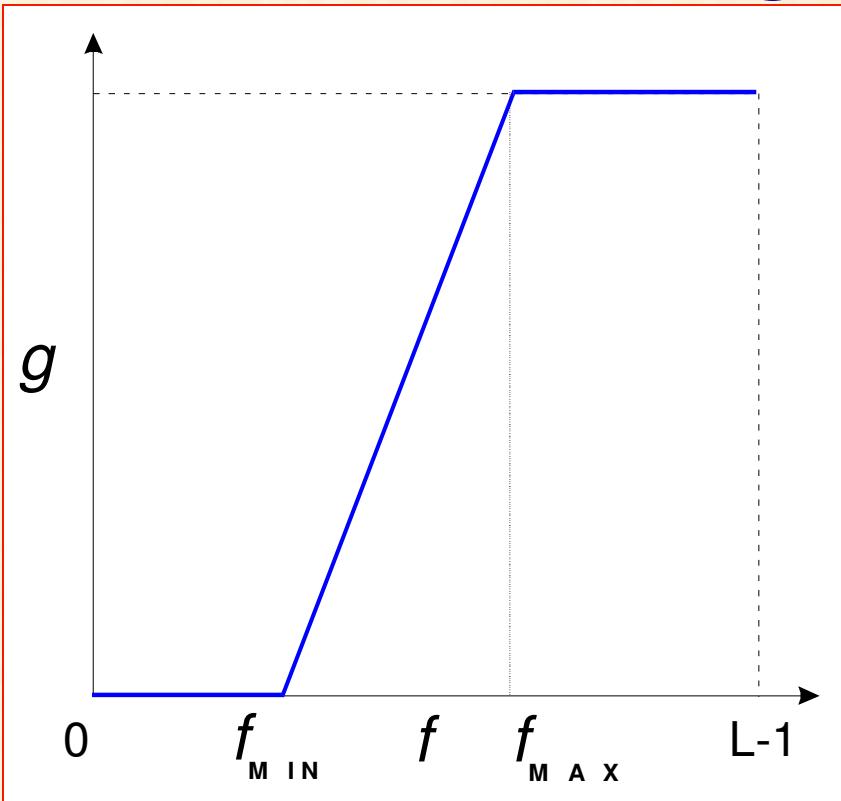
SOURCE  
IMAGE

**POINT OPERATION**

# MATLAB Demo – image histogram



# Histogram „stretching”

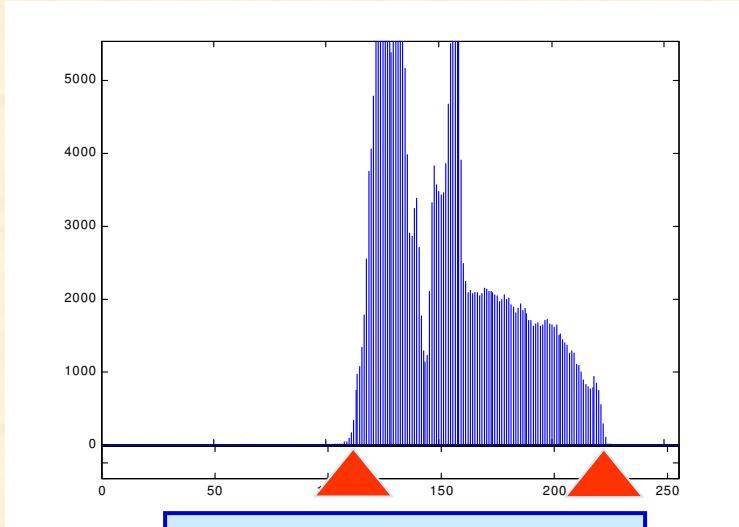


POINT OPERATION?

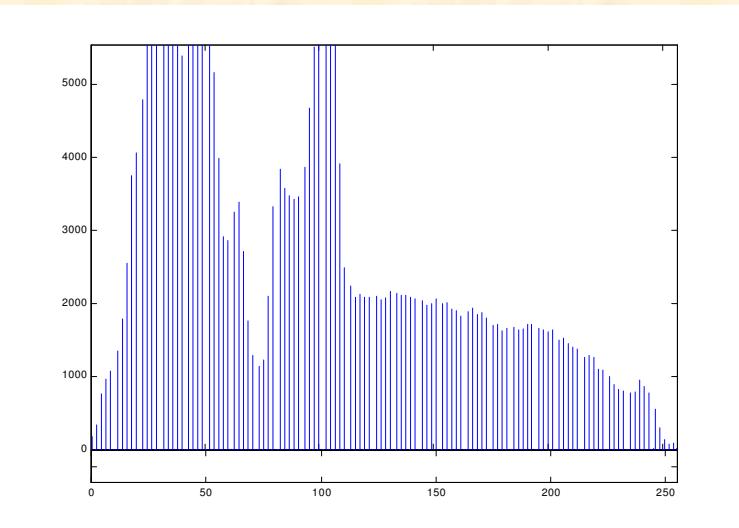
$\mathbf{G}=\text{imadjust}(\mathbf{F}, [f_{\text{MIN}} \ f_{\text{MAX}}], [g_{\text{MIN}} \ g_{\text{MAX}}])$

$$g(i,j) = \begin{cases} 0 & f(i,j) < f_{\text{MIN}} \\ \frac{L-1}{f_{\text{MAX}} - f_{\text{MIN}}} (f(i,j) - f_{\text{MIN}}), & f_{\text{MIN}} \leq f(i,j) \leq f_{\text{MAX}} \\ L-1 & f(i,j) > f_{\text{MAX}} \end{cases}$$

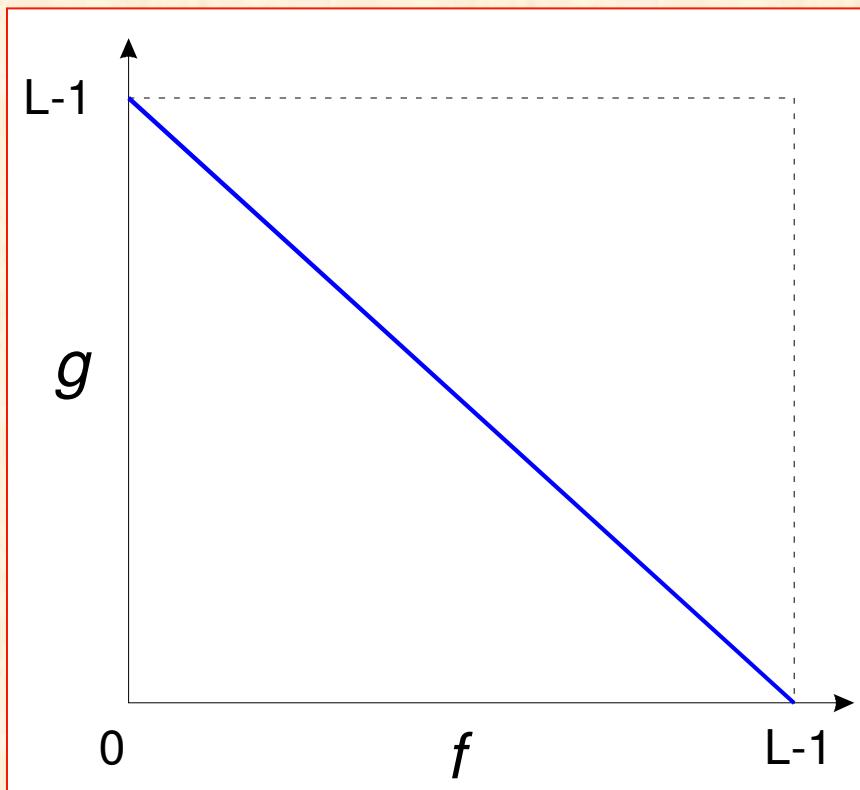
# Histogram „stretching” - example



$f_{\text{MIN}}=110, f_{\text{MAX}}=225$



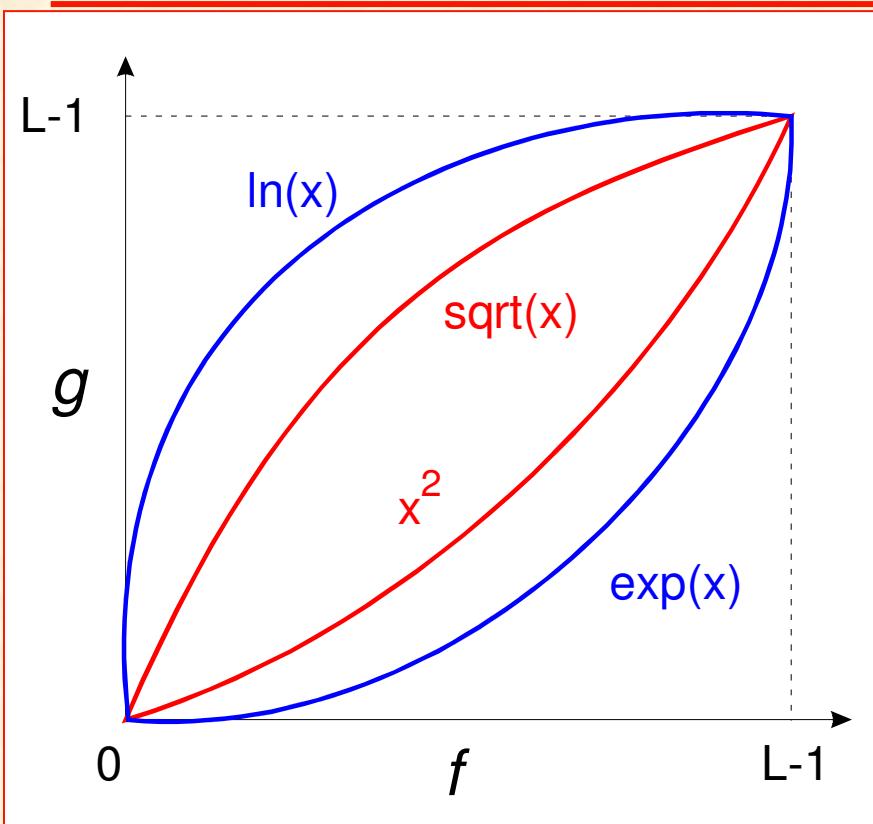
# Grayscale inversion



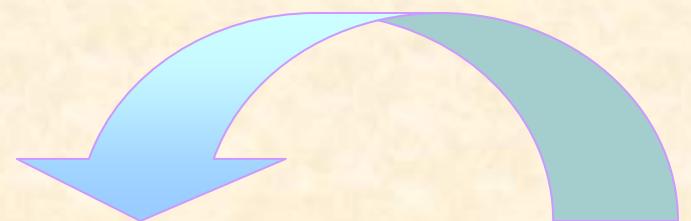
We can use look-up table to implement image point operations



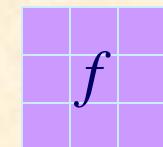
# Nonlinear grayscale transformation



$$g(i,j) = T(f(i,j))$$



OUTPUT  
IMAGE

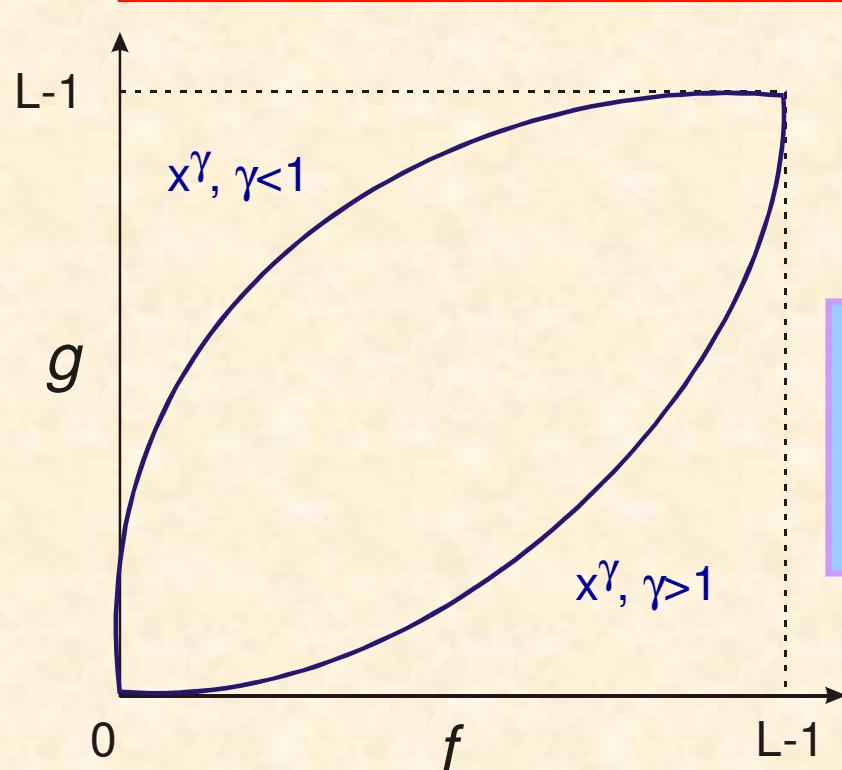


SOURCE  
IMAGE

Grayscale normalization!

POINT OPERATION

# Nonlinear grayscale transformation



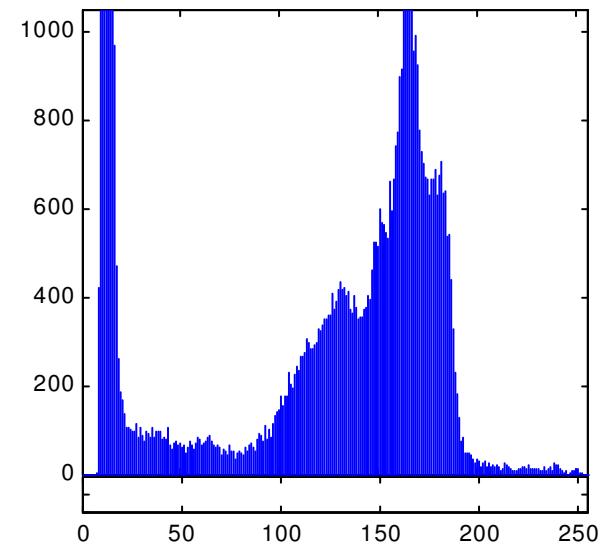
```
G=imadjust(F, [fMIN fMAX], [gMIN gMAX], γ)
```

**$\gamma$  correction**

# Nonlinear grayscale transformation - example

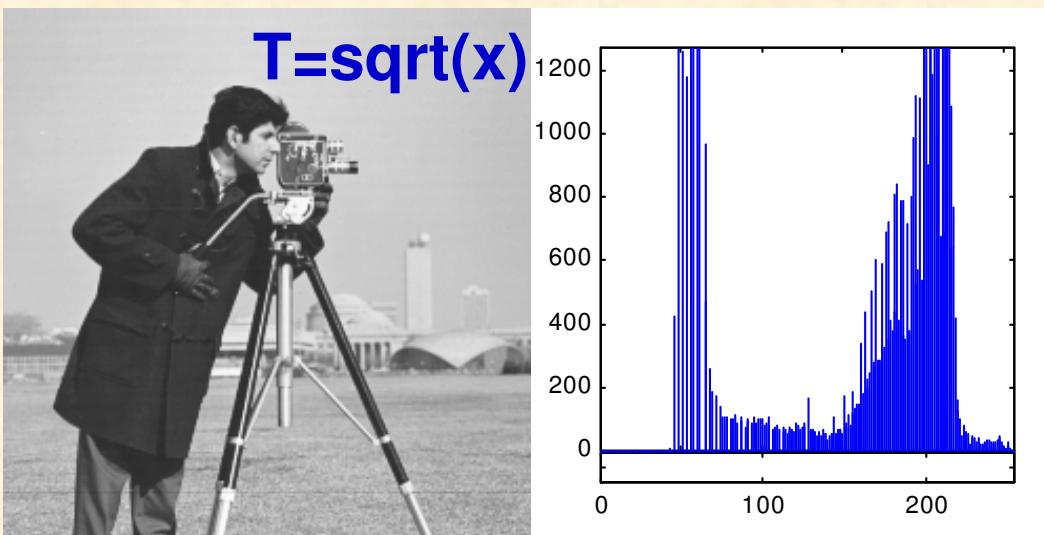
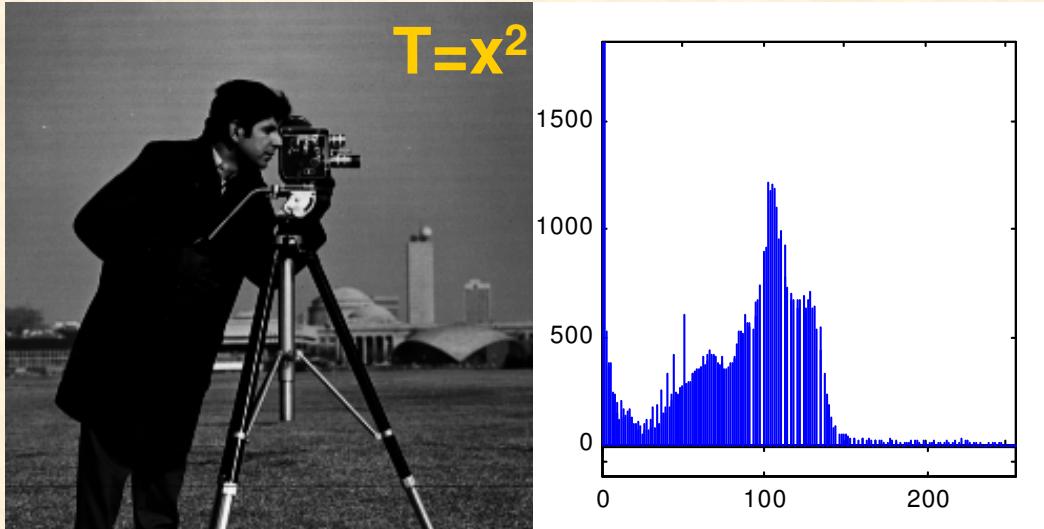
---

Source image



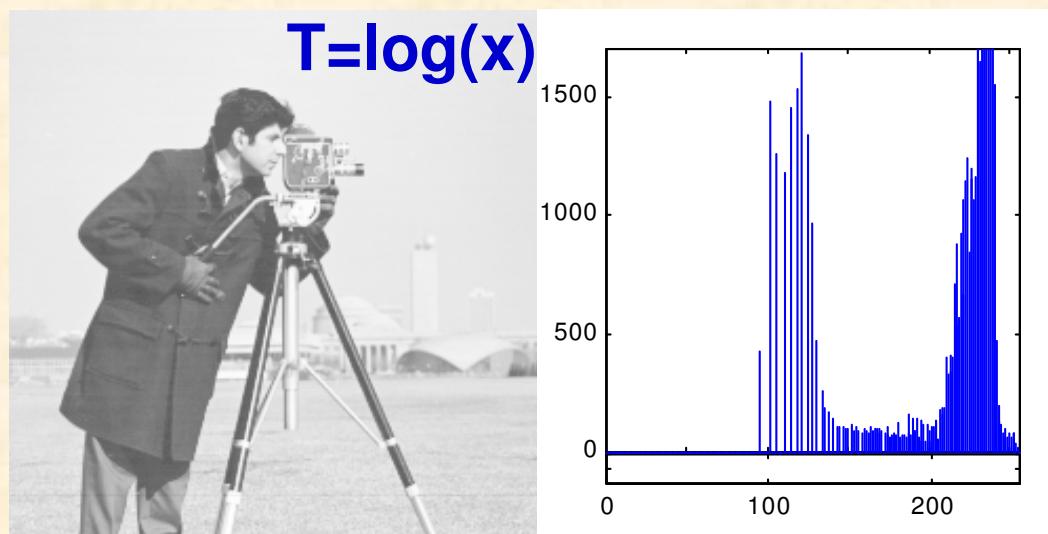
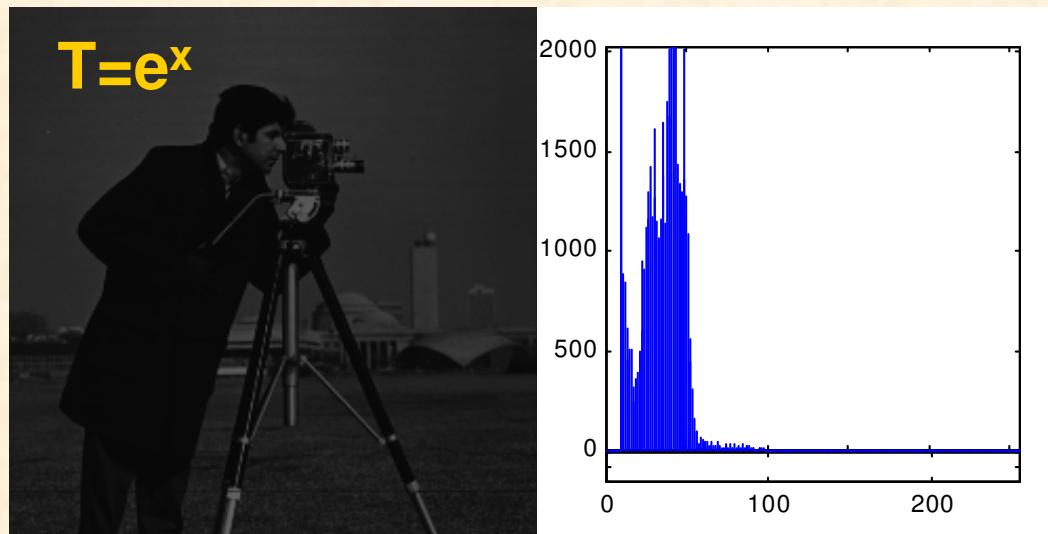
# Nonlinear grayscale transformation - example

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# Nonlinear grayscale transformation - example

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# Nonlinear grayscale transformation - algorithm

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Example: square function

normalization: minimum value - 0 -> 0

maximum value - 255 ->  $255^2$

Normalization coefficient: norm=1/255

...

for i:=1 to M do for j:=1 to N do

    g[i,j]:=round(sqr(f[i,j])\*norm);

...

# Nonlinear grayscale transformation - algorithm

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Example: square function (using look-up-table)

```
lut : array[0..255]of byte;
```

```
...
```

```
for k:=0 to 255 do lut[k]:=round(k*k*norm)
```

```
for i:=1 to M do for j:=1 to N do
```

```
    g[i,j]:=lut[(f[i,j])];
```

```
...
```

# Enhacement of a telescope moon image

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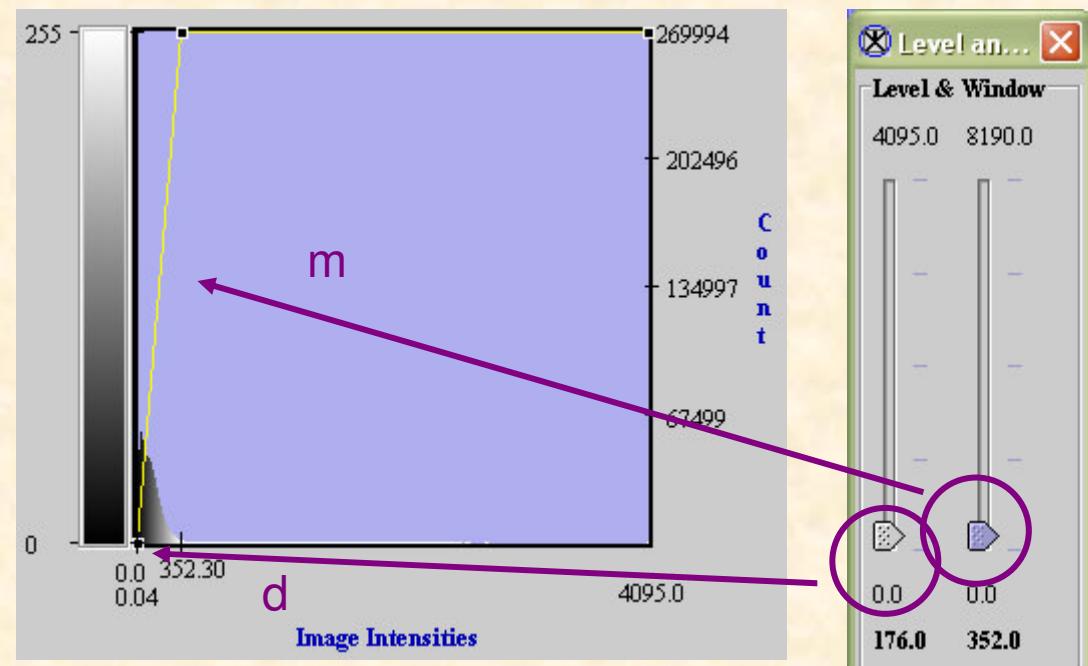


$$T = b \log(ax)$$

# Linear gray scale transformation



MR 12 bit image



histogram

Brightness/Contrast  
adjustment window

Medical Image Processing, Analysis and Visualization (MIPAV)  
by Center for Information Technology, ver. 1.29

# Image enhancement by image averaging

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Consider a noisy image:

$$g(i, j) = f(i, j) + \eta(i, j)$$

contaminated by additive noise  $\eta(i, j)$  of zero average and variance  $\sigma_\eta^2$  that is not correlated to the image.

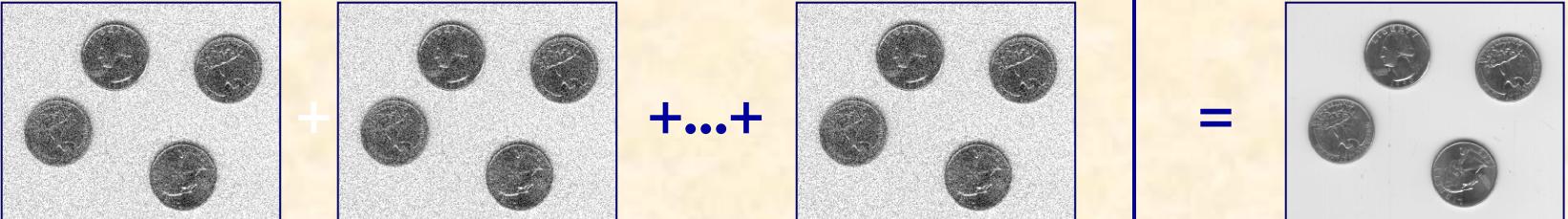
We will show that after  $N$  averagings (acquisitions) of the noisy image  $g(i, j)$  the variance of noise component will be reduced to:

$$\bar{\sigma}_\eta^2 = \frac{\sigma_\eta^2}{N}$$

# Image enhancement by image averaging

$$g(i, j) = \frac{1}{N} \sum_{k=1}^N [f(i, j) + n_k(i, j)] = f(i, j) + \frac{1}{N} \sum_{k=1}^N n_k(i, j)$$

**WARNING ! – grayscale range**

$$\frac{1}{N} \left[ \begin{array}{c} \text{Image 1} \\ + \\ \text{Image 2} \\ + \dots + \\ \text{Image N} \end{array} \right] = \text{Enhanced Image}$$


# Image enhancement by image averaging

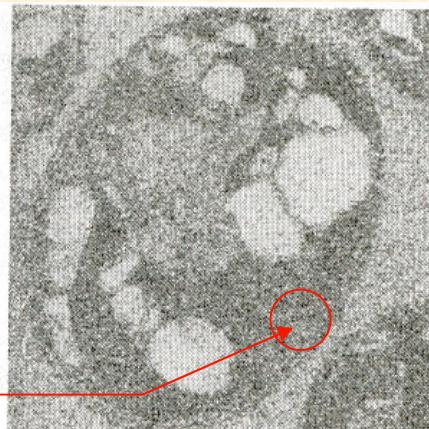
Noise variance in the averaged image:

$$\begin{aligned}\sigma_{\eta}^2 &= E\left\{\left(\frac{1}{N} \sum_{k=1}^N \eta_k\right)^2\right\} = \frac{1}{N^2} \cdot E\left\{\left(\sum_{k=1}^N \eta_k\right)^2\right\} = \\ &= \frac{1}{N^2} \cdot E\{(\eta_1 + \eta_2 + \dots + \eta_N)^2\} = \frac{1}{N^2} \cdot E\left\{\sum_{k=1}^N \eta_k^2 + 2\left(\sum_{k \neq p} \eta_k \eta_p\right)\right\} = \\ &= \frac{1}{N^2} E\left\{\sum_{k=1}^N \eta_k^2\right\} = \frac{1}{N^2} N \sigma_{\eta}^2 = \frac{1}{N} \sigma_{\eta}^2\end{aligned}$$

One can also show that the pick value of noise  $\{\eta\}$  is reduced by a factor of  $\sqrt{N}$  after  $N$  image averagings

# Image averaging – example

N=1



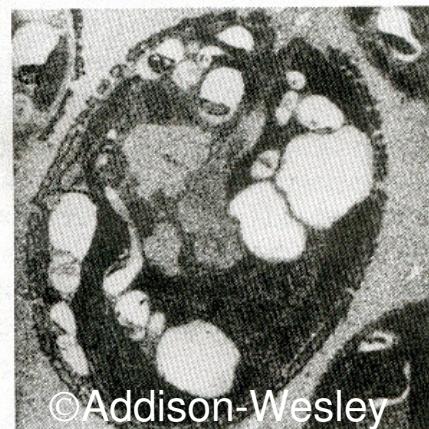
Additive Gaussian noise

N=2



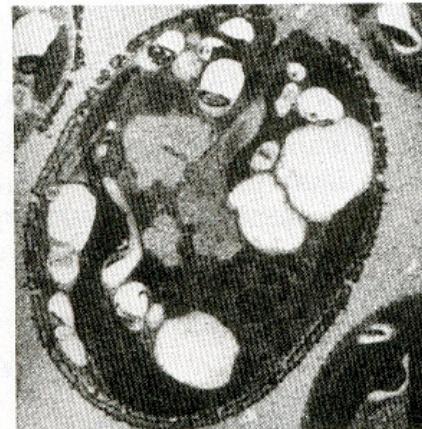
(a)

N=8



©Addison-Wesley

N=16



Microscope image of a cell

# Cumulative histogram

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*hist – image histogram, histc – cumulative histogram*

*hist : array[0..255] of longint;*

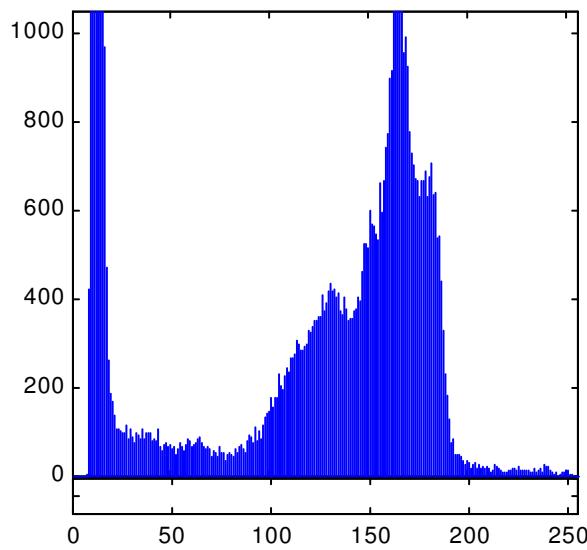
*hists : array[0..255] of single;*

$$histc[i] = \left( \sum_{k=0}^i hist[k] \right) / MN, \quad i = 0, \dots, L-1$$

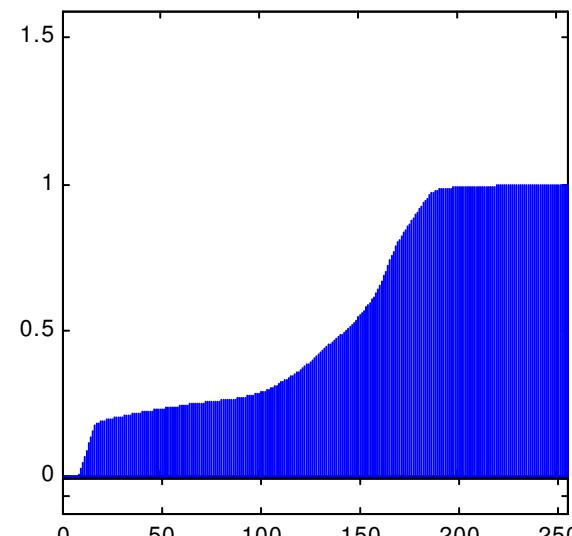
*M, N – image dimensions*



## Cumulative histogram



Histogram



Cumulative histogram

# Histogram equalization

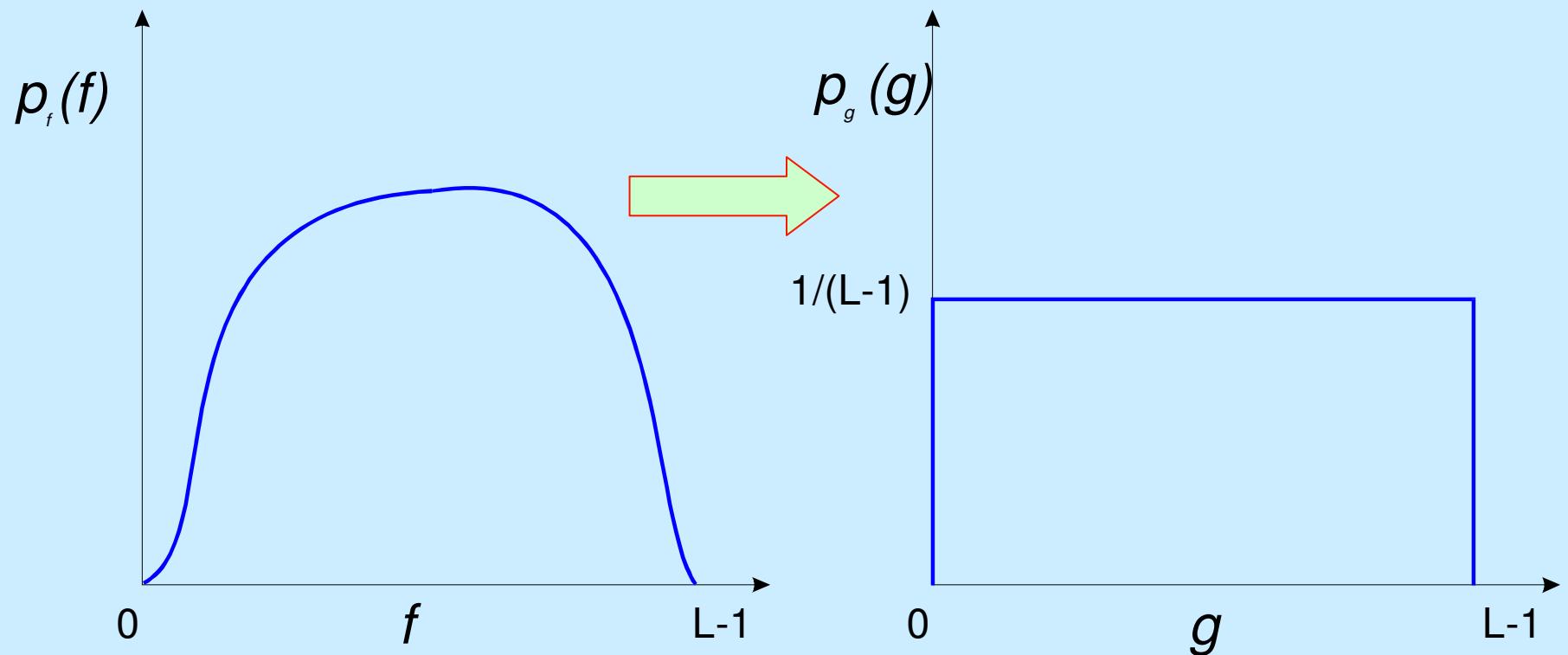
---

Histogram equalization aims at obtaining uniform statistical distribution of image gray levels (uniform probability density function)

By histogram equalization one gets:

- contrast enhancement
- image normalization

# Histogram equalization



$$p_f(f) = \text{hist}[f] / MN$$

$$p_g(g) = 1 / (L-1)$$

# Histogram equalization

---

$$\int p_f(h)dh = \int p_g(u)du$$

$$\int_0^f p_f(h)dh = \int_0^g \frac{1}{L-1} du = \frac{1}{L-1} u \Big|_0^g = \frac{g}{L-1} \quad 0 \leq f, g \leq L-1$$

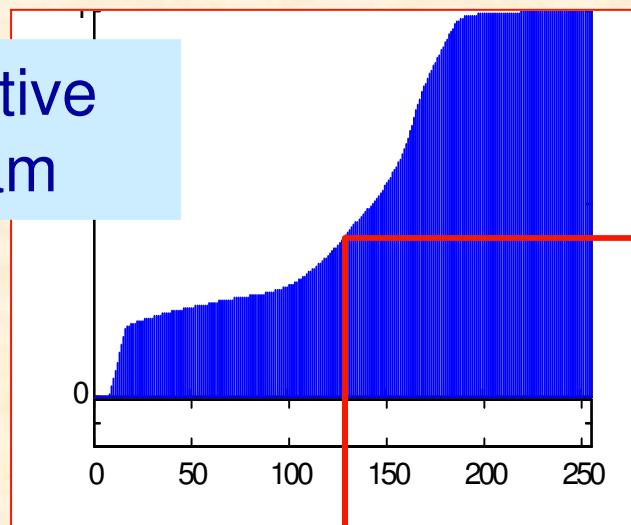
---

$$\sum_{i=0}^f p_f(i) = \frac{g}{L-1} \quad f, g = 0, 1, 2, \dots, L-1$$

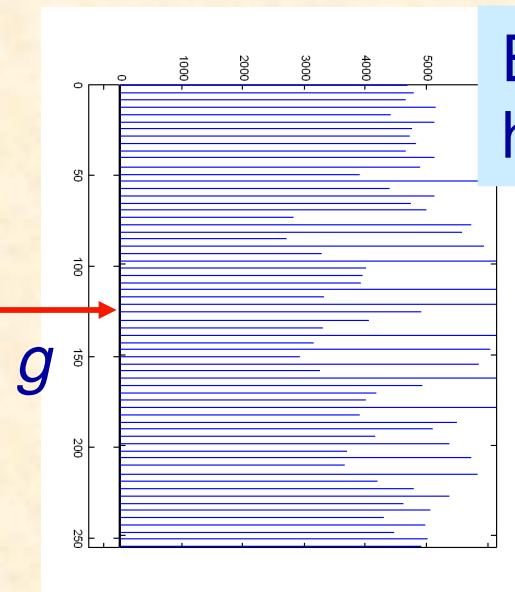
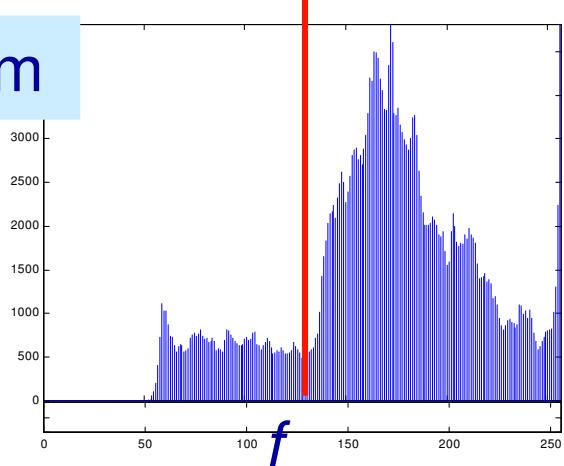
$$g = (L-1) \sum_{i=0}^f p_f(i) = (L-1) \sum_{i=0}^f \frac{hist[i]}{MN} = (L-1) histc[f]$$

# Histogram equalization

Cumulative histogram



Histogram



Equalized histogram

$$g = (L-1) \text{histc}[f]$$

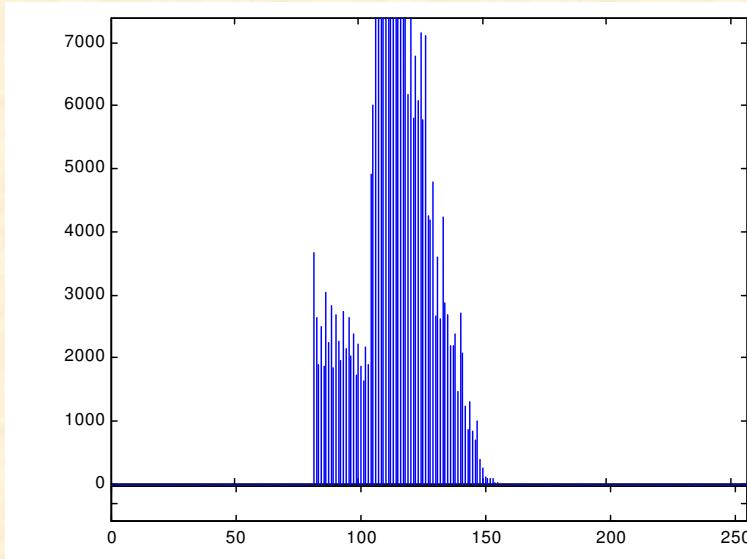
# Cumulative histogram - algorithm

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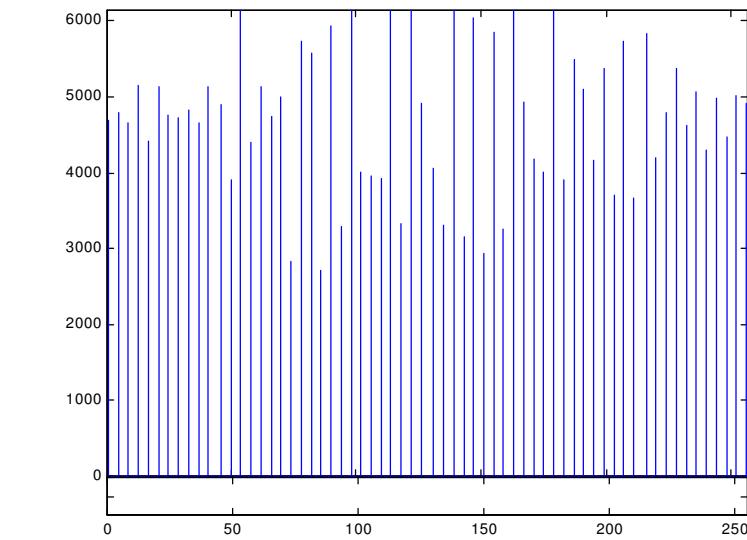
```
hist : array[0..255] of longint;  
  
histc : array[0..255] of single;  
  
...  
  
histc[0]:=hist[0];  
for k:=1 to 255 do  
    histc[k]:=histc[k-1]+hist[k];  
    ...
```

# Histogram equalization

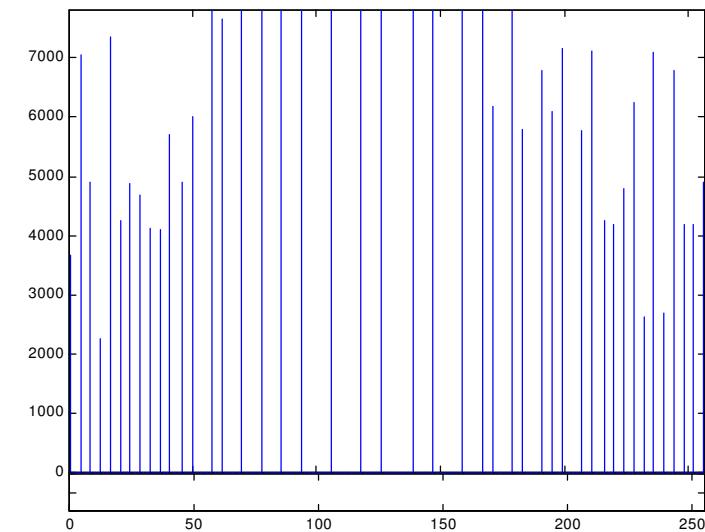
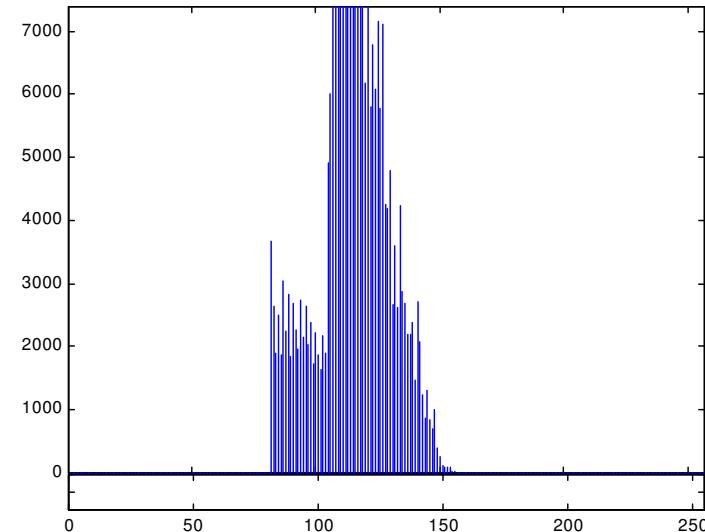
---



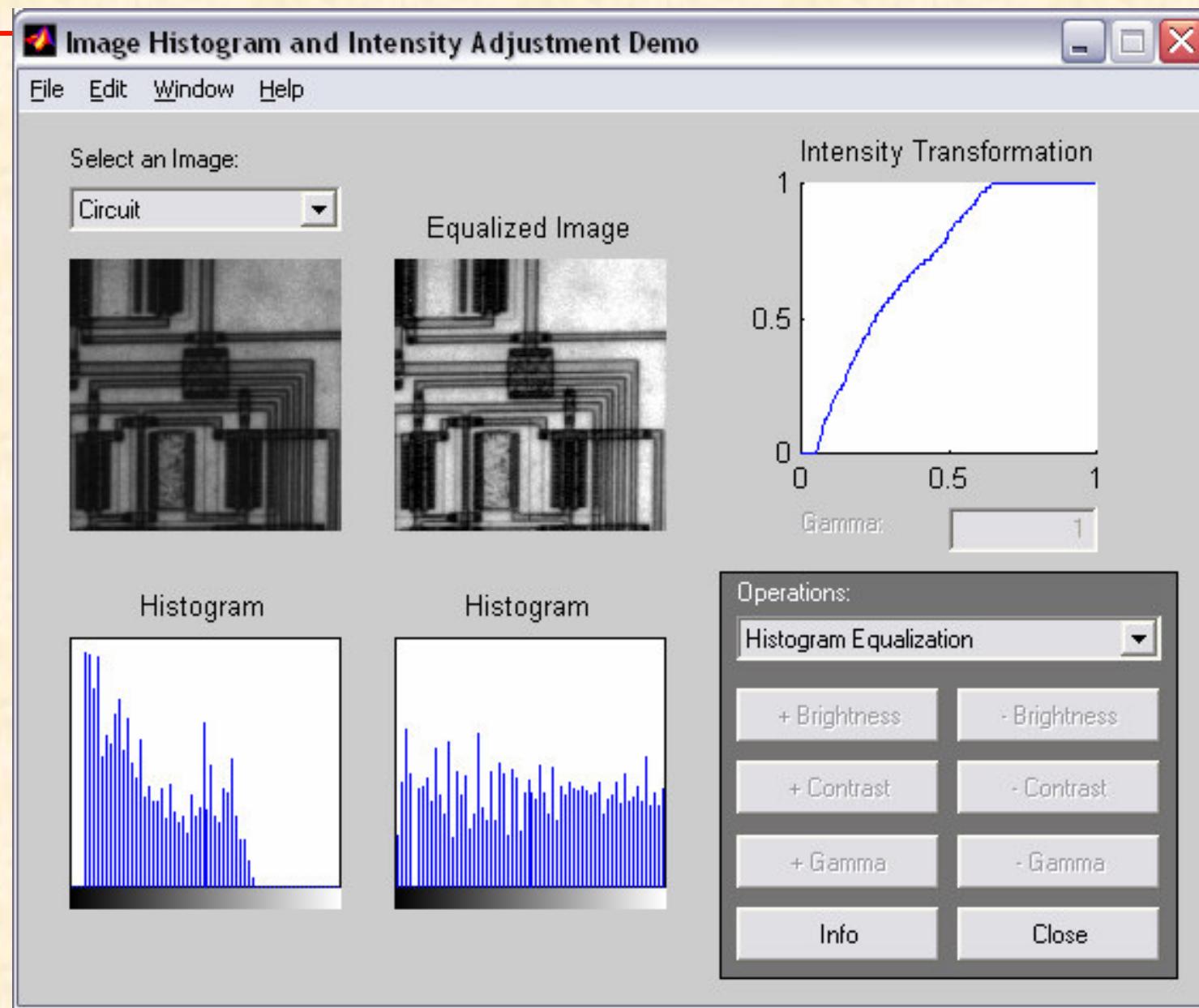
**J=histeq(I)**



# Histogram equalization - example



# MATLAB Demo – intensity adjustment



# Correction of nonuniform illumination

